

Possible Status of the Sensors:

	red LED	<u>green LED</u>	<u>output</u>
[1] Running yarn	off	on	passive
[2] Missing or stopped yarn	on	off	*active
[3] Turn-on delay is active	8 times slow blinking	on	passive
[4] Turn-on delay over, sensor at stand-by	fast blinking	on	passive

If output is "static", it is active as long as there is no running yarn;

If output is "dynamic", it is only active for approx.1s, then passive until running yarn stops again.

Possible Sequences of SENSOSTOP-Logic:

"A" Function sequence after power is turned on :

Power-on delay is active; red LED is slowly blinking 8 times and simultaneous the green LED is on (status [3]); when delay is over the green LED is off and red LED on (status [2]).

"B" Yarn is running (normal operation): After expiration of reaction time (ton) the red LED goes out and green LED goes on (status [1]).

"C" Missing or stopped yarn (yarn brakes / bobbin empty): After release time (toff) green LED goes out, red LED goes on and output Is active (stopsignal / status [2]); when yarn is running again sensor works on sequence "B".

"D" Use of sensor button or external reset :

During touching: red and green LEDs both light.

After touching: turn-on delay is active (red LED is blinking slowly 8 times and simultaneous the green LED is on = status [3]); then red LED is blinking faster (status [4]) and sensor output is passive (without time limit) until next activation by running yarn. Sensor works on sequence "B" again.

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